8.6 Joint Production by Many Agents: The Holmstrom Teams Model

- The existence of a group of agents results in <u>destroying</u> the effectiveness of the individual <u>risk-sharing</u> contracts, because observed output is a joint function of the <u>unobserved effort</u> of many agents.
- The actions of a group of players produce a joint output, and each player wishes that the others would carry out the costly actions.
- A <u>team</u> is a group of agents who <u>independently</u> choose effort levels that result in a <u>single output</u> for the entire group.

• Teams

- Players
 - \checkmark a principal and *n* agents
- The order of play
 - 1 The principal offers a <u>contract</u> to each agent *i* of the form $w_i(q)$, where *q* is total output.
 - 2 The agents decide whether or not to accept the contract.
 - 3 The agents simultaneously pick effort levels e_i , (i = 1, ..., n).
 - 4 Output is $q(e_1, \ldots, e_n)$.

- Payoffs
 - \checkmark If any agent rejects the contract, all payoffs equal zero.
 - \checkmark Otherwise,

$$\pi_{principal} = q - \sum_{i=1}^{n} w_i$$

and

$$\pi_i = w_i - v_i(e_i)$$
, where $v'_i > 0$ and $v''_i > 0$.

• The principal can <u>observe</u> output.

• The team's problem is <u>cooperation</u> between agents.

- Efficient contracts
 - Denote the efficient vector of actions by e^* .
 - An efficient contract is

$$w_i(q) = b_i \quad \text{if } q \ge q(e^*) \tag{8.9}$$
$$0 \quad \text{if } q < q(e^*),$$

where
$$\sum_{i=1}^{n} b_i = q(e^*)$$
 and $b_i > v_i(e_i^*)$.

• The teams model gives one reason to have a <u>principal</u>:

he is the residual claimant who keeps the forfeited output.

- Budget balancing and Proposition 8.1
 - The <u>budget-balancing</u> constraint
 - \checkmark The sum of the wages exactly equal the output.
 - If there is a budget-balancing constraint, <u>no</u> differentiable <u>wage contract</u> $w_i(q)$ generates an <u>efficient</u> Nash equilibrium.
 - \checkmark Agent *i*'s problem is

 $\begin{array}{lll} Maximize & w_i(q(e)) - v_i(e_i). \end{array}$

His first-order condition is

 $(dw_i/dq) (\partial q/\partial e_i) - dv_i/de_i = 0.$

 \checkmark The <u>Pareto optimum</u> solves

$$\underset{e_1,\ldots,e_n}{\text{Maximize}} q(e) - \sum_{i=1}^n v_i(e_i).$$

The first-order condition is that the marginal dollar contribution equal the marginal disutility of effort:

$$\partial q/\partial e_i - dv_i/de_i = 0.$$

 $\sqrt{-dw_i/dq} \neq 1$

Under budget balancing,

not every agent can receive the entire marginal increase in output.

 Because each agent bears the <u>entire burden</u> of his marginal effort and only <u>part</u> of the benefit,
 the contract <u>does not</u> achieve the first-best.

Without budget balancing,

if the agent shirked a little

he would gain the entire leisure benefit from shirking,

but he would lose his entire wage under the optimal contract in equation (8.9).

- With budget balancing and a linear utility function,
 the <u>Pareto optimum</u> maximizes the <u>sum</u> of utilities.
 - A Pareto efficient allocation is one where consumer 1 is as well-off as possible <u>given</u> consumer 2's level of utility.
 - \checkmark Fix the utility of consumer 2 at \overline{u}_2 .

$$\circ \quad \underset{e_1, e_2}{\text{Maximize}} \qquad w_1(q(e)) - v_1(e_1)$$

subject to

$$w_2(q(e)) - v_2(e_2) \geq \overline{u}_2$$

and

 $w_1(q(e)) + w_2(q(e)) = q(e)$

$$\circ \quad \underset{e_1, e_2}{\text{Maximize}} \qquad w_1(q(e)) - v_1(e_1)$$

subject to

$$q(e) - v_2(e_2) - \overline{u}_2 = w_1(q(e))$$

•
$$Max_{e_1, e_2}^{initial} q(e) - (v_1(e_1) + v_2(e_2)) - \overline{u}_2$$

• Discontinuities in Public Good Payoffs

• There is a <u>free rider problem</u>

if <u>several players</u> each pick a level of effort which increases the level of some <u>public good</u> whose benefits they share.

✓ Noncooperatively, they choose effort levels
 <u>lower</u> than if they could make <u>binding promises</u>.

- Consider a situation in which *n* identical risk-neutral players produce
 a <u>public good</u> by expending their effort.
 - ✓ Let e_i represent player *i*'s effort level, and let $q(e_1, ..., e_n)$ the amount of the <u>public good</u> produced, where *q* is a <u>continuous</u> function.

 \checkmark Player *i*'s problem is

$$\begin{array}{ll} Maximize & q(e_1,\ldots,e_n) - e_i. \end{array}$$

His first-order condition is

 $\partial q/\partial e_i - 1 = 0.$

 \checkmark The <u>greater</u>, first-best *n*-tuple vector of effort levels e^*

is characterized by

$$\sum_{i=1}^{n} (\partial q / \partial e_i) - 1 = 0.$$

- If the function q were <u>discontinuous</u> at e^* (for example, q = 0 if $e_i < e_i^*$ and $q = e_i$ if $e_i \ge e_i^*$ for any i), the strategy profile e^* could be a <u>Nash equilibrium</u>.
- The <u>first-best</u> can be achieved because the <u>discontinuity</u> at e^* makes every player the marginal, decisive player.
 - \checkmark If he shirks a little, output falls drastically and with certainty.

- Either of the following two modifications restores the <u>free rider problem</u> and induces <u>shirking</u>:
 - Let q be a function not only of effort but of <u>random noise</u>.
 Nature moves after the players.
 <u>Uncertainty</u> makes the expected output a <u>continuous</u> function of effort.
 - Let players have <u>incomplete</u> information about the critical value.
 Nature moves before the players and chooses *e**.
 <u>Incomplete</u> information makes the estimated output a <u>continuous</u> function of effort.

• The <u>discontinuity</u> phenomenon is common.

Examples include:

- Effort in teams (Holmstrom [1982], Rasmusen [1987])
- Entry deterrence by an oligopoly (Bernheim [1984b], Waldman [1987])
- Output in oligopolies with trigger strategies (Porter [1983a])
- Patent races
- Tendering shares in a takeover (Grossman & Hart [1980])
- Preferences for levels of a public good.

• Pareto optimum

$$\circ \quad \underset{e_1, e_2}{\text{Maximize}} \qquad q(e_1, e_2) - e_1$$

subject to

$$q(e_1, e_2) - e_2 = \overline{u}_2$$

• To solve the maximization problem,

we set up the Lagrangian function:

$$L = q(e_1, e_2) - e_1 - \lambda \{q(e_1, e_2) - e_2 - \overline{u}_2\}.$$

We have the following set of simultaneous equations:

$$\partial L/\partial \lambda = -\{q(e_1, e_2) - e_2 - \overline{u}_2\} = 0$$

$$\partial L/\partial e_1 = \partial q/\partial e_1 - 1 - \lambda \partial q/\partial e_1 = 0$$

$$\partial L/\partial e_2 = \partial q/\partial e_2 - \lambda (\partial q/\partial e_2 - 1) = 0.$$
 (A1)

Using expressions (A1) and (A2), we obtain

$$(1 - \lambda) \sum_{i=1}^{2} (\partial q / \partial e_i) = 1 - \lambda,$$

which leads to

$$\sum_{i=1}^{2} (\partial q / \partial e_i) - 1 = 0.$$

- 8.7 The Multitask Agency Problem
- Holmstrom and Milgrom (1991)
 - Often the principal wants the agent to <u>split</u> his time among <u>several tasks</u>, each with a <u>separate</u> output, rather than just working on one of them.
 - If the principal uses one of the incentive <u>contracts</u> to incentivize just one of the tasks, this "high-powered incentive" can result in the agent completely <u>neglecting</u> his other tasks and leave the principal <u>worse off</u> than under a flat wage.

- Multitasking I: Two Tasks, No Leisure
 - Players
 - \checkmark a principal and an agent
 - The order of play
 - 1 The principal offers the agent
 either an <u>incentive contract</u> of the form w(q₁) or
 a <u>monitoring contract</u> that pays m under which he pays the agent
 m₁ if he observes the agent working on Task 1 and
 m₂ if he observes the agent working on Task 2.

- 2 The agent decides whether or not to accept the contract.
- 3 The agent picks effort levels e_1 and e_2 for the two tasks such that $e_1 + e_2 = 1$,

where 1 denotes the total time available.

4 Outputs are $q_1(e_1)$ and $q_2(e_2)$, where $dq_1/de_1 > 0$ and $dq_2/de_2 > 0$ but we <u>do not</u> require decreasing returns to effort.

- Payoffs
 - \checkmark If the agent rejects the contract, all payoffs equal zero.
 - \checkmark Otherwise,

and
$$\pi_{principal} = q_1 + \beta q_2 - m - w - C$$

 $\pi_{agent} = m + w - e_1^2 - e_2^2$,

where *C*, the cost of monitoring, is \overline{C} if a monitoring contract is used and zero otherwise.

- $\checkmark \beta$ is a measure of the relative value of Task 2.
- The principal can <u>observe</u> the output from one of the agent's tasks (q_1) but <u>not</u> from the other (q_2) .

• The <u>first best</u> can be found by choosing e_1 and e_2

(subject to $e_1 + e_2 = 1$) and C to maximize the sum of the payoffs.

• Maximize $\pi_{principal} = q_1(e_1) + \beta q_2(e_2) - m - w - C$

subject to

$$\pi_{agent} = m + w - e_1^2 - e_2^2 \ge \overline{U} = 0$$

and
 $e_1 + e_2 = 1$

$$\circ \quad \begin{array}{l} \text{Maximize} \\ e_1, e_2, C \end{array} \qquad \pi_{principal} + \pi_{agent} - \overline{U} \\ \end{array}$$

subject to

$$e_1 + e_2 = 1$$

• The first-best levels of the variables

$$\sqrt{C^*} = 0$$

$$\sqrt{e_1^*} = 0.5 + 0.25 \{ \frac{dq_1}{de_1} - \beta(\frac{dq_2}{de_2}) \}$$

$$\sqrt{e_2^*} = 0.5 - 0.25 \{ \frac{dq_1}{de_1} - \beta(\frac{dq_2}{de_2}) \}$$

$$\sqrt{q_i^*} \equiv q_i(e_i^*)$$

$$(8.19)$$

 Define the minimum wage payment that would induce the agent to accept a contract requiring the first-best effort levels as

$$w^* \equiv (e_1^*)^2 + (e_2^*)^2.$$

• Can an <u>incentive contract</u> achieve the first best?

• A profit-maximizing <u>flat-wage</u> contract

 $\sqrt{w(q_1)} = w^{\circ}$ or the monitoring contract $\{w^{\circ}, w^{\circ}\}$

$$\checkmark$$
 The agent chooses $e_1^{\rm o} = e_2^{\rm o} = 0.5$.

 $\sqrt{w^{o}} = 0.5$ satisfies the participation constraint.

• A sharing-rule incentive contract

 $\sqrt{-dw/dq_1} > 0$

 \checkmark The <u>greater</u> the agent's effort on Task 1, the <u>less</u> will be his effort on Task 2.

Even if extra effort on Task 1 could be achieved for free,
the principal might not want it – and, in fact, he might be willing
to pay to stop it.

• The simplest sharing-rule (incentive) contract

 \checkmark the linear contract

$$w(q_1) = a + bq_1$$

 \checkmark The agent will pick e_1 and e_2 to maximize

$$\pi_{agent} = a + bq_1(e_1) - e_1^2 - e_2^2$$

subject to $e_1 + e_2 = 1$.

$$\sqrt{e_1^{\rm o}} = 0.5 + 0.25b(dq_1/de_1) \tag{8.23}$$

 \checkmark If $e_1^* \ge 0.5$, the linear contract will work just fine.

The contract parameters a and b can be chosen so that the linear-contract effort level in equation (8.23) is the same as the <u>first-best</u> effort level in equation (8.19), with a taking a value to extract all the surplus so the participation constraint is barely satisfied.

✓ If $e_1^* < 0.5$, the linear contract <u>cannot</u> achieve the first best with a positive value for *b*.

The contract must actually <u>punish</u> the agent for high output!

• In equilibrium,

the principal chooses some <u>contract</u> that elicits the <u>first-best</u> effort e^* , such as the forcing contract,

$$w(q_1 = q_1^*) = w^*$$

and

$$w(q_1 = q_1^*) = 0.$$

- A monitoring contract
 - The cost \overline{C} of monitoring is incurred.
 - The agent will pick e_1 and e_2 to maximize

$$\pi_{agent} = e_1 m_1 + e_2 m_2 - e_1^2 - e_2^2$$

subject to $e_1 + e_2 = 1$.

✓ The principal finds the agent working on Task *i* with probability e_i .

$$\sqrt{\pi_{agent}} = e_1 m_1 + (1 - e_1) m_2 - e_1^2 - (1 - e_1)^2$$

$$\sqrt{d\pi_{agent}/de_1} = m_1 - m_2 - 2e_1 + 2(1-e_1) = 0$$

• If the principal wants the agent to pick e_1^* ,

he should choose m_1^* and m_2^* so that

$$m_1^* = 4e_1^* + m_2^* - 2.$$

 \checkmark the binding participation constraint

$$e_1^*m_1^* + (1-e_1^*)m_2^* - (e_1^*)^2 - (1-e_1^*)^2 = 0$$

- Multitasking II: Two Tasks Plus Leisure
 - Players
 - \checkmark a principal and an agent
 - The order of play
 - 1 The principal offers the agent either an <u>incentive contract</u> of the form $w(q_1)$ or

a monitoring contract that pays m under which he pays the agent a base wage of \overline{m} plus

 m_1 if he observes the agent working on Task 1 and m_2 if he observes the agent working on Task 2.

- 2 The agent decides whether or not to accept the contract.
- 3 The agent picks effort levels e_1 and e_2 for the two tasks.
- 4 Outputs are $q_1(e_1)$ and $q_2(e_2)$, where $dq_1/de_1 > 0$ and $dq_2/de_2 > 0$ but we do not require decreasing returns to effort.

- Payoffs
 - \checkmark If the agent rejects the contract, all payoffs equal zero.
 - \checkmark Otherwise,

and

$$\pi_{principal} = q_1 + \beta q_2 - m - w - C$$

 $\pi_{agent} = m + w - e_1^2 - e_2^2$,

where *C*, the cost of monitoring, is \overline{C} if a monitoring contract is used and zero otherwise.

- $\checkmark \beta$ is a measure of the relative value of Task 2.
- The principal can <u>observe</u> the output from one of the agent's tasks (q_1) but <u>not</u> from the other (q_2) .

$\circ \quad e_1+e_2 \leq 1$

 \checkmark The amount $(1 - e_1 - e_2)$ represents <u>leisure</u>,

whose value we set equal to zero in the agent's utility function.

✓ Here <u>leisure</u> represents not time off the job,
 but <u>time on the job spent shirking</u> rather than working.

The <u>first-best</u> can be found by choosing e₁, e₂, and C
 to <u>maximize</u> the <u>sum</u> of the payoffs.

• Maximize $\pi_{principal} = q_1(e_1) + \beta q_2(e_2) - m - w - C$

subject to

$$\pi_{agent} = m + w - e_1^2 - e_2^2 \ge 0$$

and
 $e_1 + e_2 \le 1$

 $\circ \quad \underset{e_1, e_2, C}{\text{Maximize}} \qquad q_1(e_1) + \beta q_2(e_2) - C - e_1^2 - e_2^2$

subject to

$$e_1 + e_2 \leq 1$$

• The first-best levels of the variables

$$\checkmark \quad C^{**} = 0$$

$$\checkmark \quad e_1^{**} = ?$$

$$\checkmark \quad e_2^{**} = ?$$

$$\checkmark \quad q_i^{**} \equiv q_i(e_i^{**})$$

- ✓ Define the minimum wage payment that would induce the agent to accept a contract requiring the <u>first-best</u> effort levels as $w^{**} \equiv (e_1^{**})^2 + (e_2^{**})^2$.
- \checkmark <u>Positive</u> leisure for the agent in the first-best is a <u>realistic</u> case.

- Can an <u>incentive contract</u> achieve the first best?
 - A <u>flat-wage</u> contract

 $\sqrt{w(q_1)} = w^{00}$ or the monitoring contract $\{w^{00}, w^{00}\}$

 \checkmark The agent chooses $e_1^{oo} = e_2^{oo} = 0$.

A <u>low-powered</u> incentive contract is disastrous,
 because pulling the agent away from high effort on Task I
 does not leave him working harder on Task 2.

• A <u>high-powered</u> sharing-rule incentive contract

$$\sqrt{-dw/dq_1} > 0$$

- \checkmark The first-best is <u>unreachable</u> since $e_2^{oo} = 0$.
- ✓ The combination $(e_1^{00} = e_1^{**}, e_2^{00} = 0)$ is the <u>second-best</u> incentive-contract solution, since at e_1^{**} the marginal disutility of effort equals the marginal utility of the marginal product of effort.
- ✓ In that case, in the second-best the principal would push e_1^{oo} above the <u>first-best</u> level.

 The agent <u>does not</u> substitute between the task with easy-to-measure output and the task with hard-to-measure output, but between <u>each task</u> and <u>leisure</u>.

• The best the principal can do may be

to <u>ignore the multitasking feature</u> of the problem and just get the incentives right for the task whose output he <u>can</u> measure. • A monitoring contract

 \circ The <u>first-best</u> effort levels <u>can</u> be attained.

• The monitoring contract might not even be superior to the second-best incentive contract if the monitoring cost \overline{C} were too big.

 \checkmark But monitoring <u>can</u> induce any level of e_2 the principal desires.

• The base wage may even be <u>negative</u>,

which can be interpreted

- $\sqrt{}$ as a <u>bond</u> for good effort posted by the agent or
- ✓ as <u>a fee</u> he pays for the privilege of filling the job and possibly earning m_1 or m_2 .

• The agent will choose e_1 and e_2 to maximize

$$\pi_{agent} = \overline{m} + e_1 m_1 + e_2 m_2 - e_1^2 - e_2^2$$

subject to $e_1 + e_2 \le 1$.

✓ The principal finds the agent working on Task *i* with probability e_i .

$$\sqrt{\partial \pi_{agent}}/\partial e_1 = m_1 - 2e_1 = 0$$

$$\partial \pi_{agent}/\partial e_2 = m_2 - 2e_2 = 0$$

• The principal will pick m_1^{**} and m_2^{**} to induce the agent to choose

$$e_1^{**}$$
 and e_2^{**} .

$$\checkmark m_1^{**} = 2e_1^{**}$$

 $m_2^{**} = 2e_2^{**}$

- The base wage \bar{m}
 - \checkmark the binding participation constraint

$$\pi_{agent} = \overline{m} + e_1^{**} m_1^{**} + e_2^{**} m_2^{**} - (e_1^{**})^2 - (e_2^{**})^2$$
$$= \overline{m} + 2w^{**} - w^{**} = 0$$

$$\sqrt{m} = -w^{**}$$

✓ If the principal finds the agent shirking when he monitors, he will pay the agent an amount of $-w^{**}$.

✓ In the case where e₁^{**} + e₂^{**} < 1,
 the result is surprising because the principal wants the agent to take some leisure in equilibrium.

 \checkmark In the case where $e_1^{**} + e_2^{**} = 1$,

the result is intuitive.

 The key is that the base wage is important only for inducing the agent to take the job and has no influence whatsoever on the agent's choice of effort.